# Valve Actuators for 5,5mm stroke seat valve

# RLO



AMX RLO

## **Technical Data**

Control Signal AMX 424 0-10Vdc, ~ 65 kOhm (selectable by jumpers) 0-4Vdc, ~ 65 kOhm

6-10Vdc ~ 65 kOhm 2-10Vdc ~ 65 kOhm 4-20mA = 500 Ohm 3-position or On/Off

Power supply 110..240Vac.

50/60Hz +/-10%

24Vac,dc 50/60 Hz +/-10%

Power consumption 5,5VA for AXM 424

> 5,0VA for RLO 424 7,0VA for RLO 4230

0...+50°C. Working conditions

10-90%rH non-condensing

Ambient storage -20°...+70°C, 95%rH

**Running time** approx. 70sec.

**Manual Override** by 3mm hexagonal key

Action direct/reverse selectable

by jumper

Stroke 5,5mm

**Actuating force** 

Cable length plug-in type of PVC, wire 3x0,5mm2, 1,5m

**Enclosure** IP54 class II RLO 4230 IP54 class III RLO, AXM

Connection metal ring 3/4"

(on request M30x1,5)

Housing opaque polycarbonate

**Self extinguishing** V0-V1 according to UL94

Weight 360 gram

**Approvals** These products meets the demands of CE

**Features** 

Direct assembly with union nut to the neck of the valve (no tools required)

Many control signals for different applications

The stroke is adapted automatically to the valve and is over-load proof

Short Circuit proof and protected against polarity reversal

Plug-in cable for voltage supply and control

Position Indicator by LEDs

## **Application**

The valve actuator AMX/RLO is suitable to drive APSVI valve body series in HVAC systems and also other brands of valves

Two action types are available:

-floating (3-point)

- modulating Vdc and mA

The actuator is equipped with torque limit device, to power off the

actuator when the end-strokes are reched.

The assembly the actuator/valve body is done directly and easy

by a metal ring nut, no tool is necessary

The actuator is self-adjusting (AMX).

When it is powered on the stroke is automatically adapted to the

valve, no calibration is required.

The actuator is fitted with manual override by a hexagonal key.

All LED indicates the current state of the actuator:

- adjustment

- control

- end stop position

- error condition

#### Ordering

**AMX 424** Valve Actuator 24Vac/dc 0-10Vdc/4-20mA

**RLO 424** Valve Actuator Raise/Lower and On/Off 24Vac/dc

**RLO 4230** Valve Actuator Raise/Lower and On/Off 240Vac

**Automatikprodukter** 

# Valve Actuators for 5,5mm stroke seat valve

# Assembly/Installation

The actuator is factory supplied with the shaft in upper position.

Otherwise, power off the unit and insert the hexagonal key into screw of the manual override on the top of the cover.

Drive the shaft in upper position turning the key anticlockwise.

Mount the actuator onto the valve body and tighten the metal nut on the thread of bonnet valve body.

Pay attention that the clearance around the unit is sufficient to mount correctly the actuator.

Perform the electrical connections as per the wiring diagrams.

Pay attention that power supply value corrensponds to the valve of the actuator indicated on label stuck on unit.

# Status Indication by LEDs (Internal)

GREEN slowly blinking RED slowly blinking

self-adjusting in uppest position AMX self-adjusting in lowest position AMX

GREEN fast blinking RED fast blinking modulating to upper position modulating to lower position

**GREEN lighted** 

the actuator on uppest end stop or it is moving toward uppest en stop

(AMX)

**RED lighted** 

the actuator on the lowest end stop or it is moving toward lowest en stop

(AMX)

**ORANGE lighted** 

error, try 3 times to unlock and then 3 times to self-adjust AMX

jumpers setting not correct AMX

**ORANGE** blinking

permanent error AMX

RED and GREEN

blinking

**ALL LEDs OFF** 

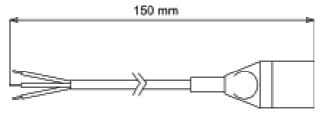
control position reached out of

end stops

Slow blinking Fast blinking

2 flashing/ second 8 flashing/ second

# **Wiring Diagram**



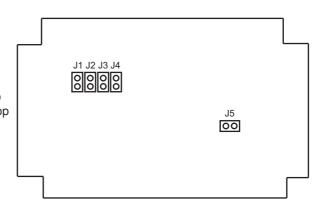
#### **RLO**

COM.	Blue
DOWN	Black
UP	Brown

#### **AMX**

COM.	Blue Black	
IN. (Y) 010 V		
24 Vca	Brown	

# **Jumpers Position on PCB AMX**



INPUT SIGNAL	JI	J2	J3	J5	J4
010 V					
04 V					
610 V	П			•	
210 V					
420 mA	:		•		
DIRECT ACTION					•
REVERSE ACTION					

#### Direct/ Reverse Action AMX

DA: 0Vdc shaft in uppest postion (A-AB valve port closed) 10Vdc shaft in lowest position (A-AB valve port open)

RA: 0Vdc shaft in lowest position (A-AB valve port open) 10Vdc shaft in uppest position (A-AB valve port closed)

Jumper unmounted

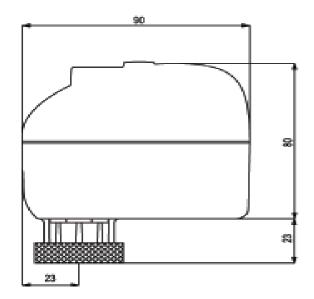


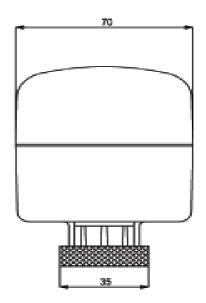
Jumper Mounted

Factory setting: DA, input signal 0-10Vdc

**RLO** 

## **Dimensions**







Each single operation done on the unit, either installation or maintenance, must be done without main supply on the units and external loads.1

Such operations are permitted only by skilled workers.

AP is not responsible for possible damages caused by an inadequate installation and/or by removed or exchanged security devices.

Choose the place in which the unit has to be mounted and follow the next instructions.

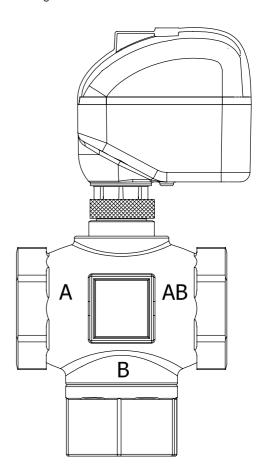
In normal conditions of use, power supply, temperature and humidity inside the unit must be always in the range indicated in the technical features.

Verify that inside the unit the ventilation is sufficient, particularly when the loads are around the maximum allowed.

Limit possible overcurrent with adequate protection (fuse or magnetothermic switch).

The actuator can not be mounted upside down.

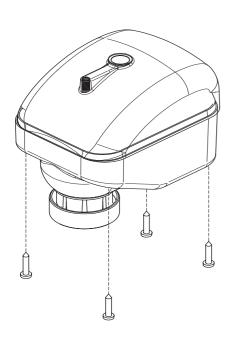
Screw the ring nut on the thread of the valve



#### Installation

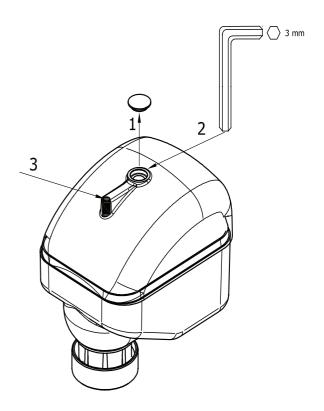
To change factory setting (input 0-10Vdc and direct action), unscrew 4 screws indicated on below picture.

Do not unscrew the 2 screws with hexagon key-way under the servomotor!



#### **Manual Override**

- 1. Remove the plug
- 2. Insert a 3mm hexagonal key
- Push the hexagonal key downward and turn counterclockwise in order the shaft reaches upper position as indicated by the indicator



# Wiring Raise/Lower or On/Off



